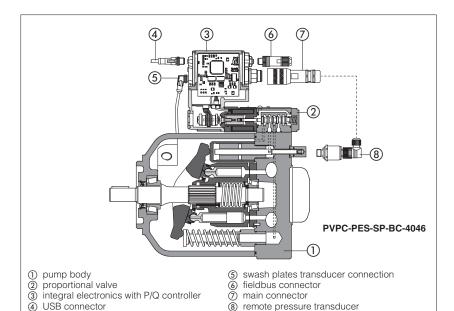


Proportional controls for PVPC pumps

analog pressure or flow, digital P/Q controls



The variable displacement axial piston pumps type PVPC, can be supplied with advanced electrohydraulic proportional controls:

- · open loop pressure control;
- open loop flow control (load sensing);
- closed loop P/Q control;

They allow to perform high dynamics and fine regulations, directly commanded from PLC or from the machine controller.

New PES digital controllers, integrated to the pump, performs alternate closed loop controls of pressure, flow and max power limitation. It is also available with optional sequence module (PERS versions) that allows to reduce close to zero the pressure to the delivery line.

SAE J744 mounting flange and shaft. Max displacement: **29**, **46**, **73**, **88 cm³/rev**

Max pressure: 280 bar working 350 bar peak

For technical characteristics and features, see tech table A160.

1 MODEL CODE

Pressure setting (only for PERS): 200 = 200 bar

PVPC X2E - PERS - SP - BC 4 046 / * 10 / Seals material: Variable displacement = NBR axial piston pump PF = FKM Series number Additional suffix for double pumps X2E = with a fixed displacement pump type PFE (see tech table A005) Options, for CZ, LQZ see sections 4: 18 =optional coil for low current Type of control (see section 7 and 8): drivers **CZ** = proportional pressure control **Electronics options for PES and** LQZ = prop. flow control (load sensing) **PERS PES-SP** = closed loop integral digital P/Q driver **PERS-SP** = as PES plus sequence module see section 11: **C** =current feedback for pressure transducer 4÷20 mA Fieldbus interfaces for PES and PERS: I = current reference input and monitor USB interface always present 4÷20 mA (omit for standard voltage **NP** = Not present reference input and monitor ±10 V) BC = CANopen
BP = PROFIBUS DP EH = EtherCAT X =with integral pressure transducer EI = EtherNet/IP EP = PROFINET IRT (only for PERS) EW= POWERLINK S = with two on-off inputs for multiple pressure PID selection (NP execution) or double power supply Size: (BC, BP, EH, EW and EP execution). 3 = for displacement 029 4 = for displacement 046 5 = for displacement 073 and 090 Direction of rotation (viewed at the shaft end) **D** = clockwise **S** = counterclockwise Max displacement: $029 = 29 \text{ cm}^3/\text{rev}$ $046 = 46 \text{ cm}^3/\text{rev}$ $073 = 73 \text{ cm}^3/\text{rev}$ $090 = 88 \text{ cm}^3/\text{rev}$ Shaft (SAE Standard): Type of PFE (for double pumps), see tech table A005 1 = keyed (7/8" for 029 - 1" for 0461 1/4" for 073 and 090)

280 = 280 bar

250 = 250 bar

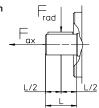
= splined (13 teeth for 029 - 15 for 046

14 for 073 and 090)

2 OPERATING CHARACTERISTICS

Pump model			*-3029	PVPC-*-4046		PVPC-*-5073		PVPC-*-5090	
Displacement	[cm³/rev]	2	9	46	3	7	3	8	8
Theorical max flow at 1450 rpm	[l/min]	42		66,7		105,8		127,6	
Max working pressure / Peak pressure [bar]		280/350		280/350		280/350		250/315	
Min/Max inlet pressure	[bar abs.]	0,8 / 25 0,8 / 25		0,8 / 25		0,8 / 25			
Max pressure on drain port [bar abs.]		1,	5	1,	5	1,	,5	1,	5
Power consumption at 1450 rpm and at maximum pressure and displacement	[kW]	19	,9	31	,6	50), 1	54	,1
Max torque on the first shaft	[Nm]	Type1 200	Type5 190	Type1 230	Type5 330	Type1 490	Type5 620	Type1 490	Type5 620
Max permissible load on drive shaft [N]	Fax Frad	1000 1500			00 00	•	00	20 30	
Speed rating	[rpm]	500 ÷	3000	500 ÷	2600	500 ÷	2600	500 ÷	2200

External load position



Notes: For speeds over 1800 rpm the inlet port must be under oil level with adequate pipes.

Maximum pressure for all models with water glycol fluid is 160 bar, with /PE options is 190 bar.

Max speed with /PE options and water glycol fluid is 2000/1900/1600/1500 rpm respectively for the four sizes.

 F_{ax} = axial load F_{rad} = radial load

3 GENERAL NOTES

Atos proportional pumps are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

The electrical signals of the pump (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics. EN-982).

4 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

		Any position. The drain port must be on the top of the pump. Drain line must be separated and		
Assembly position		unrestricted to the reservoir and extended below the oil level as far from the inlet as possible.		
		Suggested maximum line lenght is 3 m.		
Subplate surface finishing		Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101)		
		-CZ, -LQZ execution = -20°C ÷ +70°C		
Ambient temperature range		-PES and -PERS executions = -20°C ÷ +60°C		
Storage temperature range		-20°C ÷ +70°C		
Coil resistance R at 20°C	pump size 3	$3 \div 3.3 \Omega$ for standard 12 Vpc coil; $13 \div 13.4 \Omega$ for 18 Vpc coil (only for version CZ, LQZ)		
Coll resistance it at 20 C	pump size 4, 5	$3.8 \div 4.1 \Omega$ for standard 12 Vbc coil; $12 \div 12.5 \Omega$ for 18 Vbc coil (only for version CZ, LQZ)		
Max. solenoid current		2,6 A for standard 12 Vpc coil; 1,5 A for standard 18 Vpc coil (only for version CZ, LQZ)		
Max. power		CZ, LQZ execution = 35 Watt; PES, PERS executions = 50 Watt		
Power supply for pressure tra	ansducer (PE*S)	24 Vpc		
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards		
Insulation class		ISO 13732-1 and EN982 must be taken into account		
Protection degree to DIN EN60529		CZ, LQZ executions = IP65 PES, PERS executions = IP66/67 with mating connector		
Duty factor		Continuous rating (ED=100%)		
EMC, climate and mechanic	al load	See technical table G004		
		I		

5 SEALS AND HYDRAULIC FLUID - for other fluids not included in above table, consult our technical office

Seals, recommended temperature fluid NBR seals = -20° C $\div +60^{\circ}$ C, with HFC hydraulic fluids = -20° C $\div +50^{\circ}$ C FKM seals = -20° C $\div +80^{\circ}$ C			- +50°C	
Recommended viscosity	20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s - max start-up viscosity 1000 mm²/s			
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 μm (β10 ≥75 recommended)			
Hydraulic fluid	Suitable seals type	Classification	Ref. Standard	
Mineral oils	NBR, FKM	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water	FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water	NBR	HFC	100 12022	

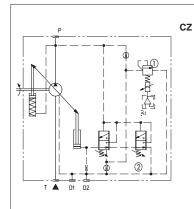
Note: for other fluids not included in above table, consult our technical office

6 ELECTRONIC DRIVERS

Pump model			CZ,	LQZ			PES, PERS
Drivers model	E-MI-AC-01F	E-BM-AC	E-ME-AC	E-MI-AS-IR	E-BM-AS-PS	E-BM-AES	E-RI-PES
Type	Analog			Digital			
Format	plug-in DIN 43700 to solenoid UNDECAL		EUROCARD	plug-in to solenoid	DIN-ra	il panel	Integral to valve
Data sheet	G010	G025	G035	G020	G030	GS050	GS215

Note: for power supply and communication connector see table GS215

7 OPEN LOOP ELECTROHYDRAULIC CONTROLS



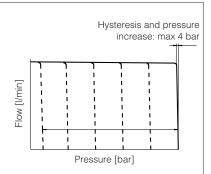
Proportional pressure control

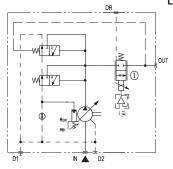
Open loop control of the pump max pressure The pumps displacement, and thus the flow, remains constant as far the pressure in the circuit reaches the value set on the proportional pilot valve ①, then the flow is reduced to maintain the circuit pressure to the value set by the electronic reference signal to the proportional valve. In this conditions the pressure in the circuit can be continuosly modulated by means of the reference signal.

Proportional pressure setting range: see below pressure control diagram.

Compensator setting range ②: 20÷350 bar (315 bar for 090)

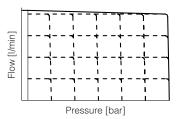
Compensator factory setting ②: 280 bar (250 bar for 090)





LQZ Proportional flow (load-sensing)

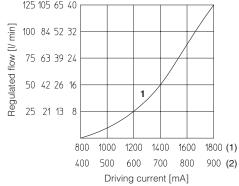
Open loop control of the pump flow independent to the cyrcuit load. The pump displacement is self adjusted to maintain a costant pressure drop across the proportional flow control valve ①. The pump flow can be continuosly regulated by modulating the proportional valve ①.

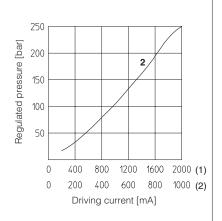


Diagrams for CZ, LQZ Regulation diagrams

- 1 = Flow control
- 2 = Pressure control
- (1) for standard 12 VDC coil
- (2) for 18 Vpc coil

Pump size 88 73 46 29 cm³/rev 125 105 65 40

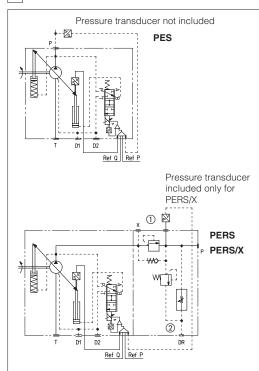




8 CONNECTIONS FOR CZ AND LQZ

	SOLENOID POWER SUPPLY CONNECTOR					
PIN	Signal description					
1	SUPPLY					
2	SUPPLY					
3	GND					

9 P/Q DIGITAL CONTROLLER



Digital P/Q controller integrates the alternate pressure and flow regulation with the electronic max power limitation.

A remote pressure transducer must be installed on the system and its feedback

has to be interfaced to the pump digital driver. Flow control is active when the actual system pressure is lower than the pressure reference input signal: the pump flow is regulated according to the flow reference input. Pressure control is activated when the actual pressure grows up to the pressure reference input signal: the pump flow is then reduced in order to regulate and limit the max system pressure (if the pressure tends to decrease under its command value, the flow control returns active). This option allows to realize accurate dynamic pressure profiles.

Following fieldbus interfaces are available:

- BC CANopen interfaceBP PROFIBUS DP interface
- EH EtherCAT interface
- EW POWRELINK interface
- FL FtherNet/IP interface
- EP PROFINET IRT interface

The pumps with BC, BP, EH, EW, EI and EP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit.

The digital control ensures high performances as flow and pressure linearity (see diagram 1), better flow knee (see diagram 2), internal leakage compensation (controlled flow independent to the load variations).

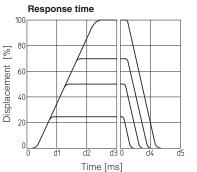
PVPC-PES

basic version, without sequence module and without pressure transducer, which has to be installed on the main line and wired to the 12 poles connector of the integral digital electronics

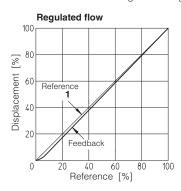
PVPC-PERS

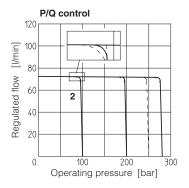
version with sequence module RESC 2 which grant a minimum piloting pressure (18 bar) when the actual pressure falls below that value. Without pressure transducer

 $\begin{array}{c} \textbf{PVPC-PERS/X} \text{ as PERS version plus integral pressure transducer, with output} \\ \text{signal } 4 \div 20 \text{ mA, factory wired to the pump digital electronics} \\ \end{array}$ through a cable gland.



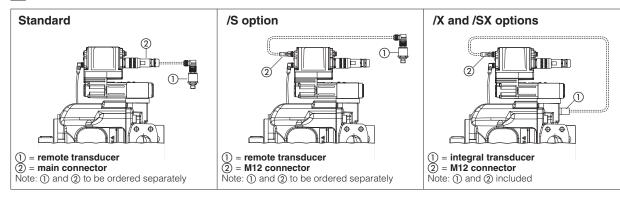
T	d1	d2	d3	d4	d5	
Type pump	[ms]					
PVPC-PE(R)S-3029	30	60	90	30	60	
PVPC-PE(R)S-4046	40	80	120	40	80	
PVPC-PE(R)S-5073	50	100	150	50	100	
PVPC-PE(R)S-5090	60	120	170	60	120	





Response time of displacement variation for a step change of the electronic reference signal.

10 PRESSURE TRANSDUCER SELECTION



The pressure transducer type E-ATR-8 must be ordered separately (see tech table **GS465**) For /X option the pressure transducer with output signal 4 ÷ 20 mA is integral to the pump.

Pump code: Pressure transducer code: PVPC-PER(S)-*/200 E-ATR-8/250 PVPC-PER(S)-*/250 E-ATR-8/400 PVPC-PER(S)-*/280 E-ATR-8/400 PVPC-PER(S)-*/200/*/C E-ATR-8/250/I PVPC-PER(S)-*/250/*/C E-ATR-8/400/I E-ATR-8/400/I PVPC-PER(S)-*/280/*/C

11 ELECTRONICS OPTIONS FOR PES AND PERS

Standard execution provides on the 12 pin main connector:

 $\label{eq:power_supply} \textit{Power supply} \qquad \textit{-The power supply to the solenoids must be appropriately stabilized or rectified and filtered: apply at least a 10000 μF/40 V capa-$

citance to single phase rectifiers or a 4700 $\mu\text{F}/40~\text{V}$ capacitance to three phase rectifiers.

A safety fuse is required in series to each driver power supply: 2,5 A fuse time lag.

Reference input signals - The driver controls in closed loop both the pump flow and pressure proportionally to the external reference input signals.

The driver is designed to receive two analog reference input signals both referred to the common mode signal zero (AGND). The inputs range and polarity are software selectable within the ± 10 VDC maximum range; default settings are $0 \div +10$ VDC. Driver with fieldbus interface can be software set to receive reference values directly by the machine control unit (fieldbus

master); in this case the analog reference input signals can be used for start-up and maintenance operations.

Monitor output signals - The driver generates an analog output signals proportional to the actual pump swashplate position and to the actual pres-

sure on the pump outlet line; the monitor output signals can be software set to show other signals available in the driver

(e.g. analog reference, fieldbus reference, pilot spool position).

The output polarity is software selectable within ±10 VDC maximum range; default settings are 0 ÷ +10 VDC.

Fault Output Signal -Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20mA input, pressure/swashplate/pilot transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC (pin 11 referred to pin2). Fault status is not affected by the

status of the Enable input signal

Enable Input Signal -To enable the driver, supply a +VDC on pin 3 referred to pin 2: when the Enable signal is set to zero the pump functio(only for /S and /SX options) ning is disabled but the driver current output stage is still active.

Note: a minimum booting time between 400 and 800 ms has be considered from the driver energizing with the 24 VDC power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

For other functions, see tech table GS215

11.1 Option /C

The pump electronics is set to receive 4÷20 mA feedback signal from the remote pressure transducer, instead of the standard 0÷10 V.

11.2 Option /I

It provides 4÷20 mA current reference and monitor signals instead of the standard 0÷+10 VDC.

It is normally used in case of long distance between the machine control unit and the pump or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

11.3 Option /X (only for -PERS)

Option providing the presence of the pressure transducer, with output signal 4÷20 mA, integral to the pump and factory wired to the PES electronics through a cable gland.

11.4 Option /S

Multiple pressure PID selection (only for /S and /SX options in NP execution)

Two on-off input signals are available on the main connector to select one of the four pressure PID parameters setting, stored into the driver.

Supply a 24 Vpc or a 0 Vpc on pin 9 and/or pin 10, to select one of the PID settings as indicated by binary code table at side. Gray code can be selected by software.

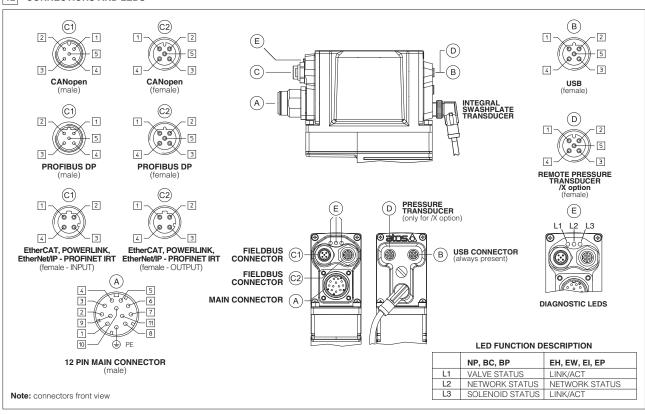
Logic power supply (only for /S and /SX options in BC, BP, EH, EW, EI or EP executions)

Separate power supply (pin 9,10) allow to cut solenoid power supply (pin 1,2) while maintaining active diagnostics, USB and fieldbus communication.

A safety fuse is required in series to each driver power supply: $500 \, \text{mA}$ fast fuse.

11.5 Possible combined options: /CS, /SX, /CI, /IS, /IX, /CIS and /ISX.

12 CONNECTIONS AND LEDS



PID SET SELECTION

SET 3

24 VDC

SET 4

24 VDC

24 VDC

SET 2

24 VD

0

PIN

9

10

SET 1

0

12.1 Main connector signals (Standard, Standard with /X option) - 12 pin

(A)	

PIN	Standard	/X	TECHNICAL SPECIFICATIONS	NOTES
1	V+		Power supply 24 VDC Rectified and filtered: VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)	Input - power supply
2	V0		Power supply 0 Vbc	Gnd - power supply
3	FAULT		Fault (0 Vpc) or normal working (24 Vpc), referred to V0	Output - on/off signal
4	INPUT-		Negative reference input signal for Q_INPUT+ and P_INPUT+	Gnd - analog signal
5	Q_INPUT+		Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
6	Q_MONITO	R	Flow monitor output signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option. Referred to V0	Output - analog signal Software selectable
7	P_INPUT+		Pressure reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
8	P_MONITOR		Pressure monitor output signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option. Referred to V0	Output - analog signal Software selectable
9	D_IN		Function software selectable between: power limitation enable (default), multiple pressure PID selection or pump enable (24 Vpc) / disable (0 Vpc). Referred to V0	Input - on/off signal
10	TR+		Remote pressure transducer input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /C option	Input - analog signal Software selectable
		NC	Do not connect	
11	TR-		Negative pressure transducer input signal for TR+	Input - analog signal
11		NC	Do not connect	
PE	EARTH		Internally connected to driver housing	

Note: these connections are the same of Rexroth A10VSO axial piston pumps, model SYDFEE and SYDFEC

12.2 Main connector signals (/S and /SX option) - 12 pin $\begin{tabular}{l} \end{tabular}$

/		\
1	Λ	١.

PIN	/S an	d /SX	TECHNICAL SPECIFICATIONS	NOTES
- 114	NP	Fieldbus	TECHNICAL OF ECH ICATIONS	NOTES
1	V+		Power supply 24 VDC Rectified and filtered: VRMs = 20 ÷ 32 VMAX (ripple max 10 % VPP)	Input - power supply
2	V0		Power supply 0 Vpc	Gnd - power supply
3	ENABLE ref	erred to: VL0	Enable (24 Vpc) or disable (0 Vpc) the pump	Input - on/off signal
4	Q_INPUT+		Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
5	INPUT-		Negative reference input signal for Q_INPUT+ and P_INPUT+	Input - analog signal
6	Q_MONITOR referred to:		Flow monitor output signal: ±10 Vbc / ±20 mA maximum range Defaults are 0÷+10 Vbc for standard and 4 ÷ 20 mA for /I option	Output - analog signal Software selectable
7	P_INPUT+		Pressure reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
8	P_MONITOI V0	referred to: VL0	Pressure monitor output signal: ±10 Vpc / ±20 mA maximum range Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /I option	Output - analog signal Software selectable
9	D_IN0		Function software selectable between: multiple pressure PID 0 selection (default) or power limitation enable. Referred to V0	Input - on/off signal
		VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
10	D_IN1		Function software selectable between: multiple pressure PID 1 selection (default) or power limitation enable. Referred to V0	Input - on/off supply
		VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
11	FAULT referred to: V0 VL0		Fault (0 Vpc) or normal working (24 Vpc)	Output - on/off signal
PE	EARTH		Internally connected to driver housing	
			Internally connected to driver housing	

Notes: these connections are the same of Moog radial piston pumps, model RKP-D do not disconnect VL0 before VL+ when the driver is connected to PC USB port

12.3 Communications connectors (B) - (C)

	B USB connector - M12 - 5 pin always present				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	+5V_USB	Supply for external USB Flash Drive			
2	ID	USB Flash Drive identification			
3	GND_USB	Signal zero data line			
4	D-	Data line -			
5	D+	Data line +			

(C1) (© BP fieldbus execution, connector - M12 - 5 pin				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	+5V	Termination supply signal			
2	LINE-A	Bus line (high)			
3	DGND	Data line and termination signal zero			
4	LINE-B	Bus line (low)			
5	SHIELD				

Notes: (1) shield connection on connector's housing is recommended

(C1) (©1) ©2) BC fieldbus execution, connector - M12 - 5 pin					
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)				
1	CAN_SHLD	Shield				
2	not used	©1 - ©2 pass-through connection (2)				
3	CAN_GND	Signal zero data line				
4	CAN_H	Bus line (high)				
	CANLL	Rue line (low)				

©1) ©2 EH, EW, EI, EP fieldbus execution,connector - M12 - 4 pin								
PIN	SIGNAL TECHNICAL SPECIFICATION (1)							
1	TX+	Transmitter						
2	RX+	Receiver						
3	TX-	Transmitter						
4	RX-	Receiver						
Housing	SHIELD							

(2): pin 2 can be fed with external +5V supply of CAN interface

12.4 Pressure transducer connector - M12 - 5 pin - only for /S, /X, /SX options (D1) - (D2)

PIN	SIGNAL	TECHNICAL SPECIFICATION	Voltage	Current
1	VF +24V	Power supply +24Vpc	Connect	Connect
2	TR	Signal transducer ±10 Vpc / ±20 mA maximum range, software selectable Defaults are 0÷+10 Vpc for standard and 4 ÷ 20 mA for /C option	Connect	Connect
3	AGND	Common GND for transducer power and signals	Connect	/
4	NC	Not Connect	/	/
5	NC	Not Connect	/	/

13 PROGRAMMING TOOLS - see tech table GS500

Pump's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options:

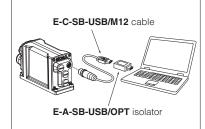
E-SW-BASIC PS (Serial) support: NP (USB) IR (Infrared) E-SW-FIELDBUS support: BC (CANopen) BP (PROFIBUS DP) EH (EtherCAT)

EW (POWERLINK) EI (EtherNet/IP) EP (PROFINET IRT) pumps with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ) support:

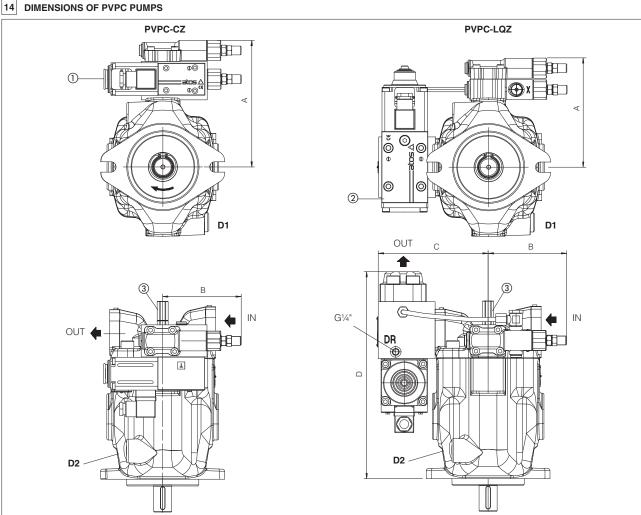
WARNING: drivers USB port is not isolated!

The use of isolator adapter is highly recommended for PC protection (see table **GS500**)

13.1 - USB connection



E-SW-*/PQ



- ① = Proportional pressure control valve
- 2 = Proportional flow control valve
- 3 = Regulation screw for max displacement. Adjustable range 50% to 100% of max displacement (not available for versions PES, PERS and PERS/X). In case of double pump the regulation screw is not always available, please contact our technical office.

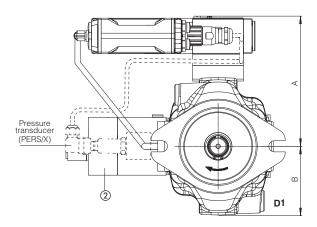
Drawing shows pumps with clockwise rotation (option D): pumps with counterclockwise rotation (option S) will have inlet and outlet ports inverted and consequently also the position of the control devices.

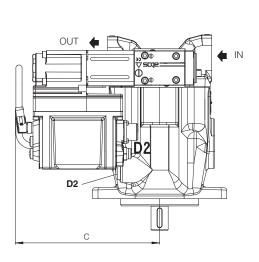
Pump type	Version	Α	В	С	D	IN	оит	D1, D2	Mass (kg)
DVDO * 0000	cz	168	111	-	-	Flange SAE 3000 1 1/4"		1/2" BSPP	22
PVPC-*-3029	LQZ	144	111	132	257				24
PVPC-*-4046	CZ	177	111	-	-	Flange SAE 3000 1 1/2"	Flange SAE 6000 1"	1/2" BSPP	28
T VI C4040	LQZ	153	111	156	293				33,6
PVPC-*-5073	CZ	190	111	-	-	Flange SAE	3/4" BSPP -	36,9	
PVPC-*-5090	LQZ	166	111	163	328			44	

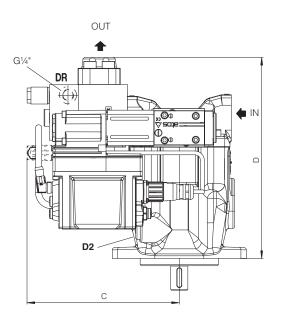
PVPC-PES

1
1

PVPC-PERS PVPC-PERS/X (dotted line)







- ① = Proportional valve with integral digital P/Q controller
- ② = Sequence module

Drawing shows pumps with clockwise rotation (option D): pumps with counterclockwise rotation (option S) will have inlet and outlet ports inverted and consequently also the position of the control devices.

Pump type	Version	Α	В	С	D	IN	ОИТ	D1, D2	Mass (kg)
	PES	170	103,5	190	-	Flange SAE 3000 1 1/4"	Flange SAE 6000 3/4"	1/2" BSPP	21,6
PVPC-*-3029	PERS	170	103,5	200	262,5				26
	PERS/X	190	103,5	200	262,5				26,4
	PES	178	103,5	190	-	Flange SAE - 3000 1 1/2"		1/2" BSPP	27,6
PVPC-*-4046	PERS	178	103,5	220	299		Flange SAE 6000 1"		33,7
	PERS/X	178	103,5	220	299				34,1
PVPC-*-5073	PES	190	103,5	190	-	Flange SAE 3000 2"	Flange SAE 6000 1 1/4"	3/4" BSPP	36,6
PVPC5073 PVPC-*-5090	PERS	190	103,5	230	337				46,7
F VF C5090	PERS/X	190	103,5	230	337				47,1